Project 01 – Robot Kinematics

MTRN4230 – UNSW School of Mechanical and Manufacturing Engineering

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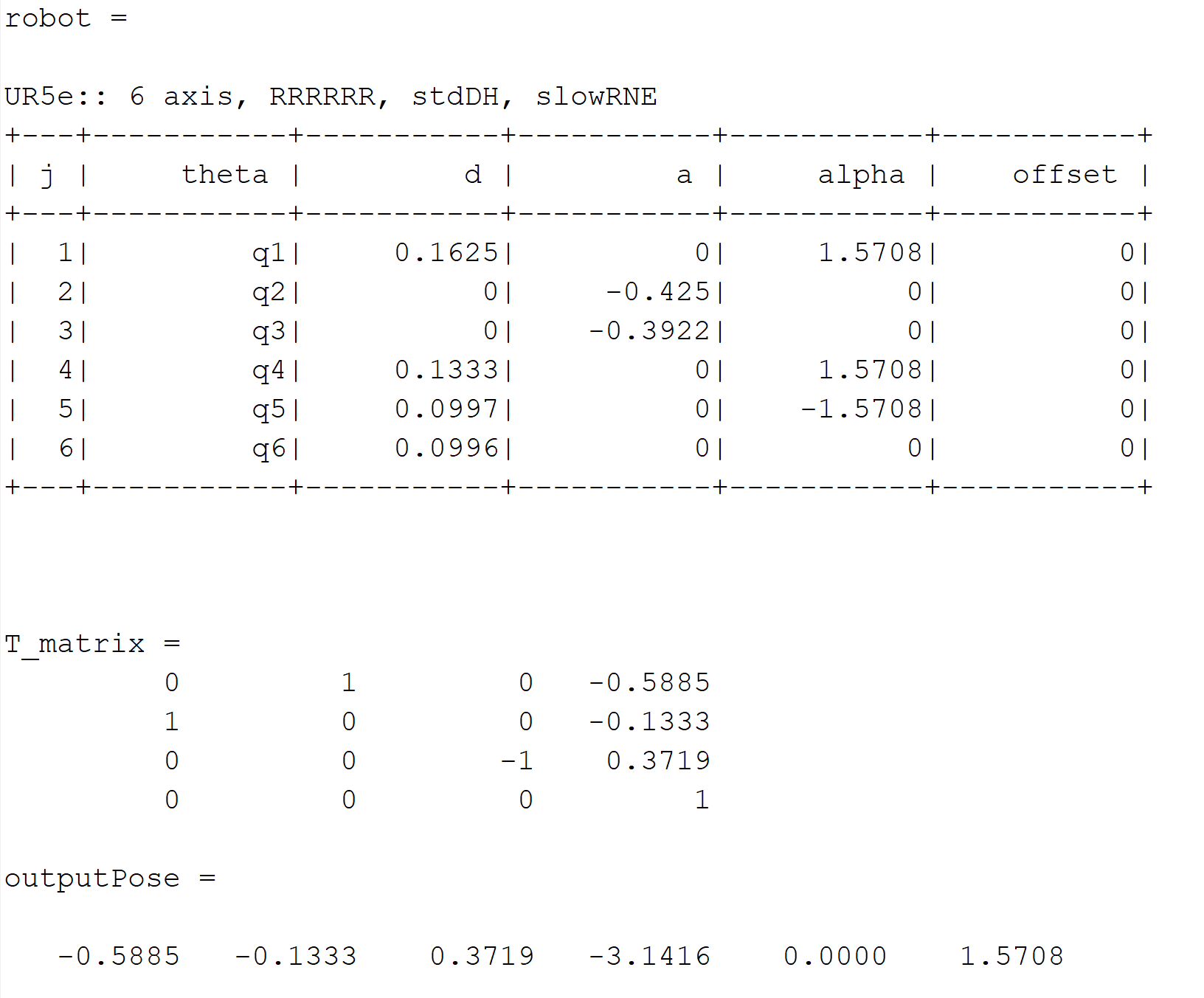
Part A: Dynamics forward kinematics

* Done via MATLAB

Part B: UR5e modelling

1. Manual calculations

(2)



(3) 